

Impact of IERS Conventions (2010) on VLBI-derived reference frames

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Motivation

- The global geodetic observing system (GGOS) has set its product goals to be 1mm (position) and 0.1 mm y⁻¹ (velocity) accuracy
- Of course this goal can only be achieved, if state-of-the-art models are consistently applied
- IERS and other conventions are necessary for ensuring the consistency of products determined by a combination of various observation techniques or analysis centers
- IERS Conventions specify those models, which have to be applied for all space-geodetic techniques
- This talk wants to address, that not all the models specified by IERS Conventions, however, are in deed the current best available ones

Outline

- Beside other model changes some updates from IERS Conventions 2003 to the current 2010 version are:

IERS Conventions	2003	2010
Reference Frames		
CRF	ICRF-Ext.1	ICRF2
TRF	ITRF2000	ITRF2008
Ephemerides	DE/LE 405	DE/LE 421
Displacements of reference points		
Ocean loading	Scherneck, no convention	Scherneck, 342 constituent tides (Agnew implementation)
Atmosphere loading	no convention	Ray & Ponte (2003), van Dam
Pole tide	mean pole (2003)	mean pole (2010)
Ocean pole tide	no convention	Desai (2002)

VLBI solution setup

- 2044 X-/S-band IVS VLBI sessions between 1984.0 and 2001.0 (for testing ITRF2000 against ITRF2008) excluding VCS sessions
- 46 common, non-mobile sites, excluding SYOWA (only observed 4 sessions)
- 538 common radio sources of ICRF-Ext.1 and ICRF2 observed at least 4 times per session
- Reference solution applies the standards and conventional models of IERS Conventions (2003) + IVS analysis standards (Nothnagel, 2008)
- Test solutions subsequently apply one new model of IERS Conventions (2010)

VLBI solution setup

„time series“ approach

„frame“ approach

session-wise NNR on
all sources

NNR on the 212 ICRF-Ext.1
defining sources

free

free

session-wise NNR+NNT
on all stations

NNR+NNT on positions and velocities
of 27 ITRF2008 (VLBI) stations

unconstrained

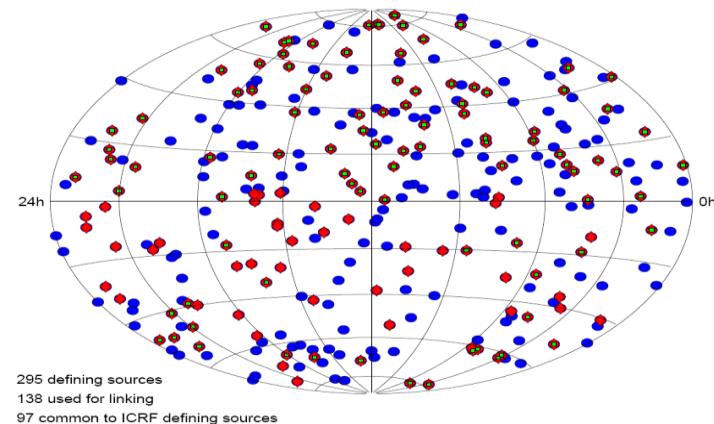
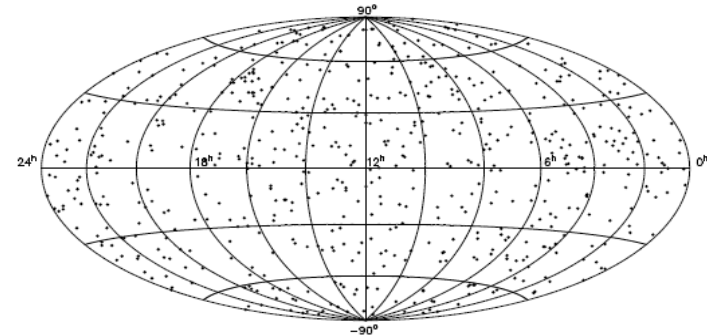
least-squares estimation
using time series

inversion of accumulated
NEQ + datum



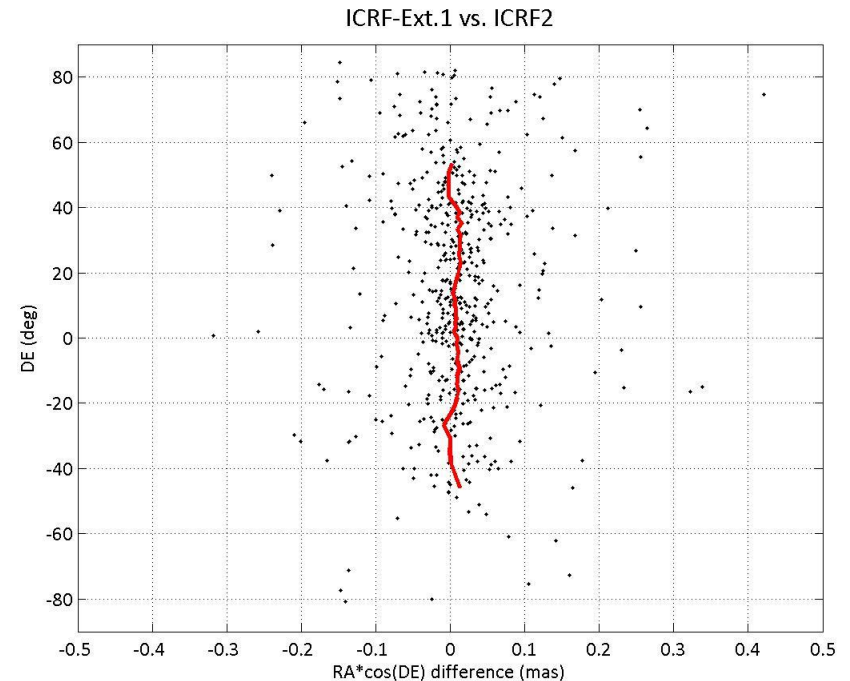
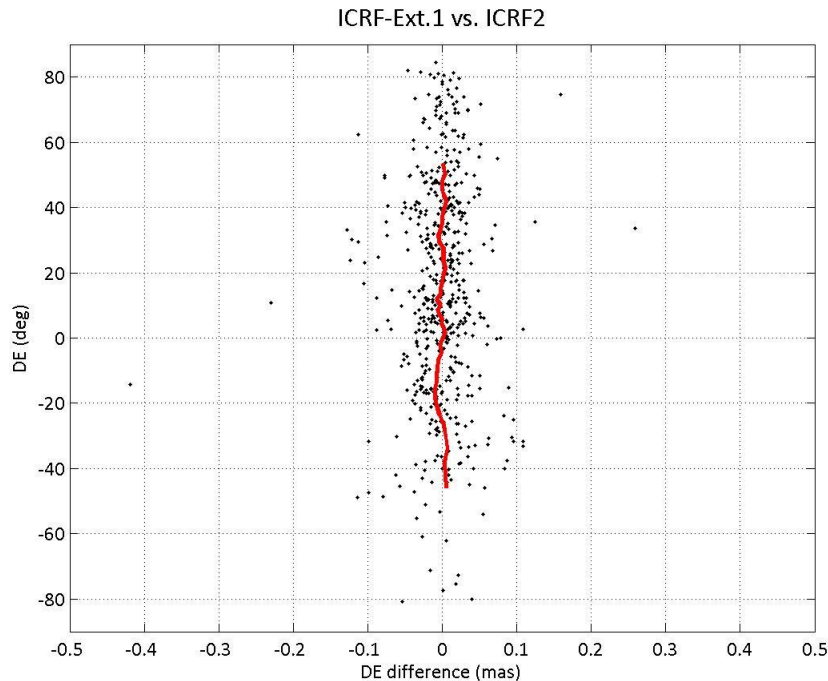
ICRF-EXT.1 vs. ICRF2

- ICRF-Ext.1 (IERS, 1999):
212 defining, 294 candidate, 102 other, 59 new, 667 total
(here 538 in common)
 - Axes stability: 20 μas
 - Mean positional error: 250 μas
- ICRF2 (IERS, 2009):
295 defining, 1114 candidate, 39 other, 1448 total
(here 538 in common)
 - Axes stability: 10 μas
 - Mean positional error: 40 μas



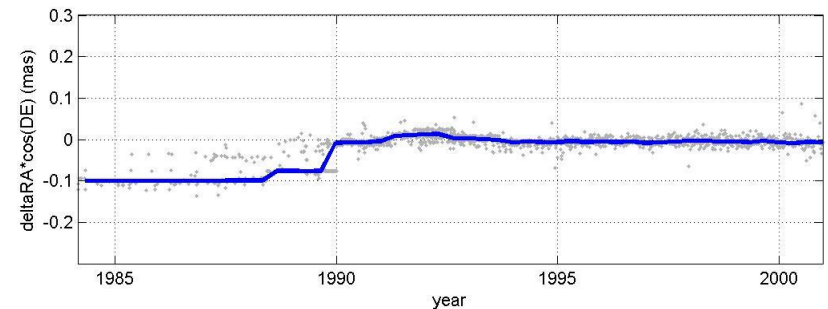
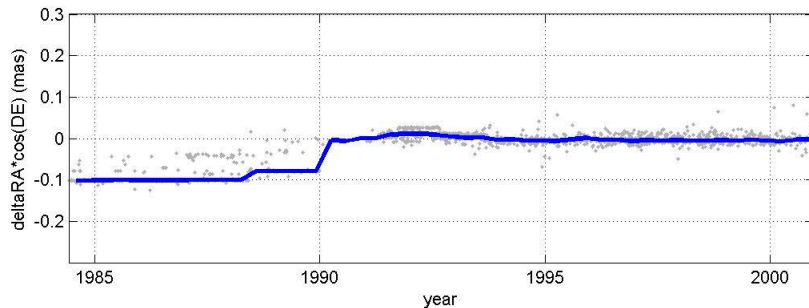
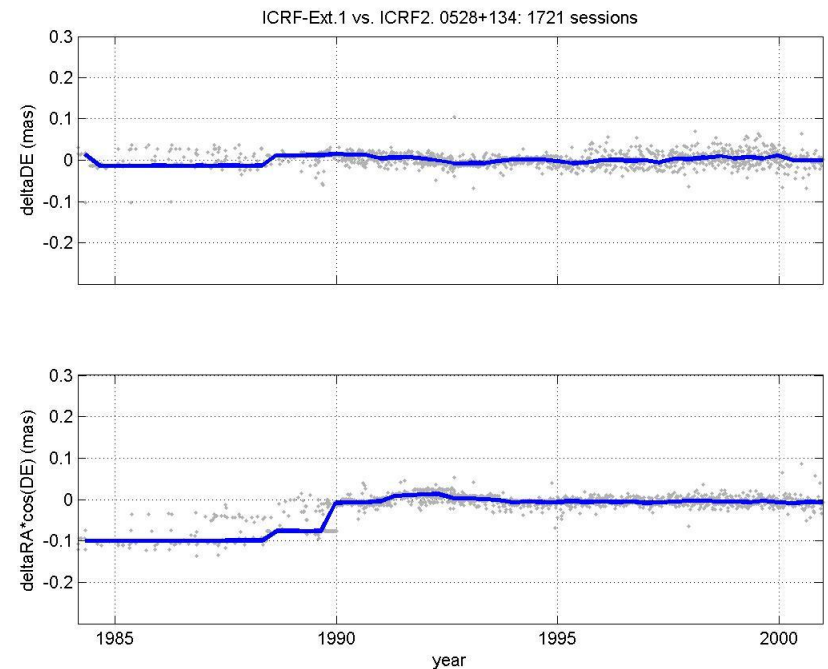
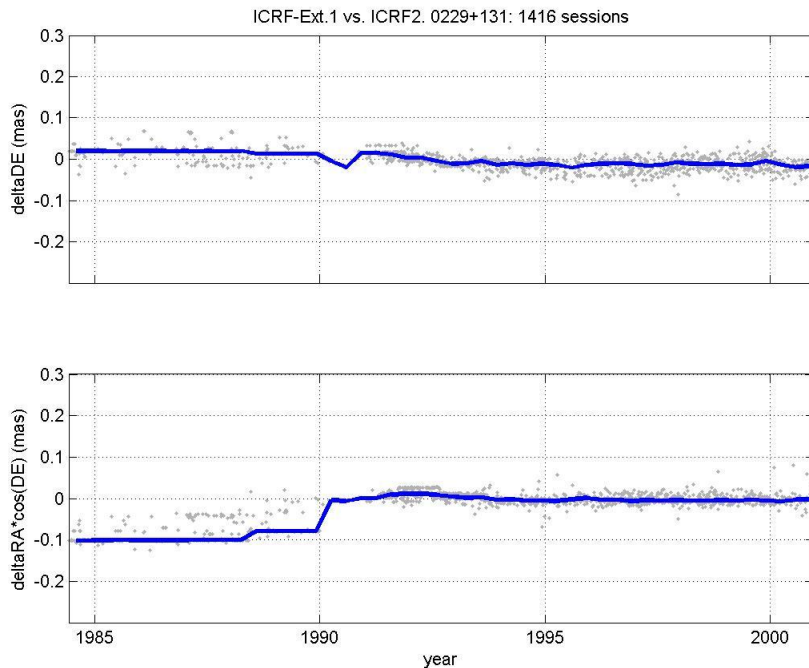
ICRF-EXT.1 vs. ICRF2

- CRF: no systematic differences in DE or RA, standard deviation is about $10 \mu\text{as}$ (at the axes stability level of ICRF2)



ICRF-EXT.1 vs. ICRF2

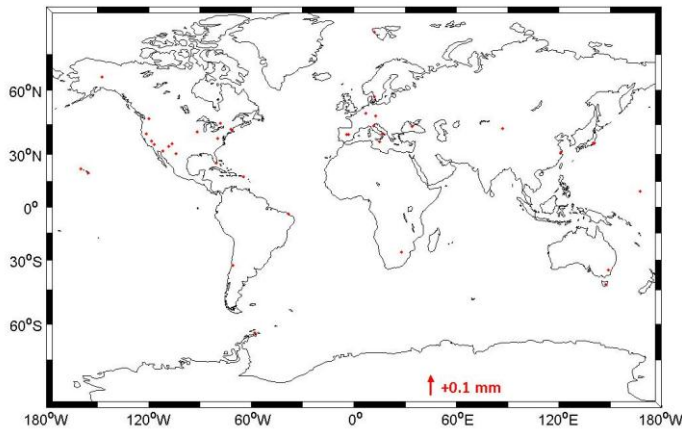
- Radio source time series: Several sources show a shift in the RA-differences at 1990 of about $100 \mu\text{as}$
- Before 1990 too few (about 15) sources were observed per session
→ not enough to correctly adjust radio source coordinates on a session basis



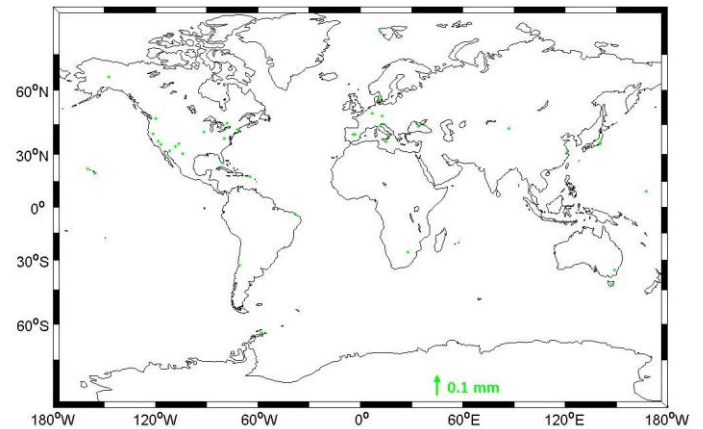
ICRF-EXT.1 vs. ICRF2

- TRF and station time series: no significant effect, small DE-/RA-differences among ICRF-Ext.1 and ICRF2 and good de-correlation of sources and stations

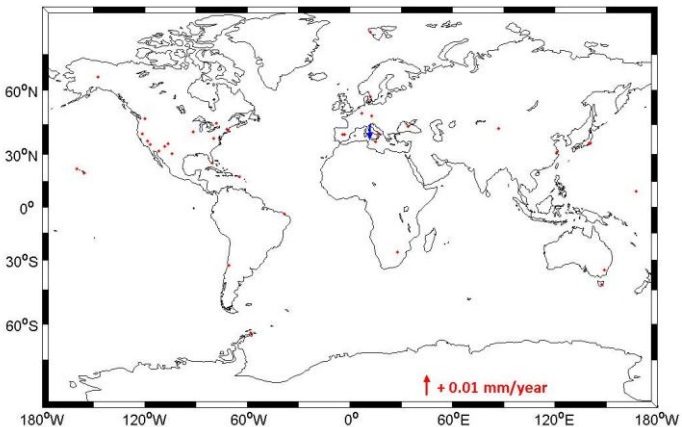
ICRF-Ext.1 vs. ICRF2: height difference



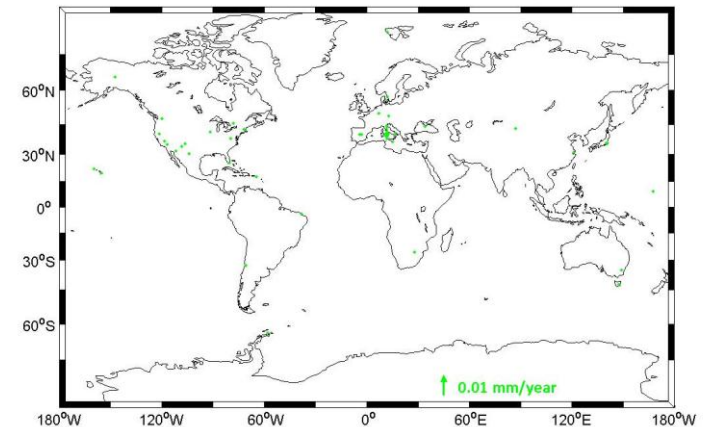
ICRF-Ext.1 vs. ICRF2: horizontal difference



ICRF-Ext.1 vs. ICRF2: height velocity



ICRF-Ext.1 vs. ICRF2: horizontal velocity



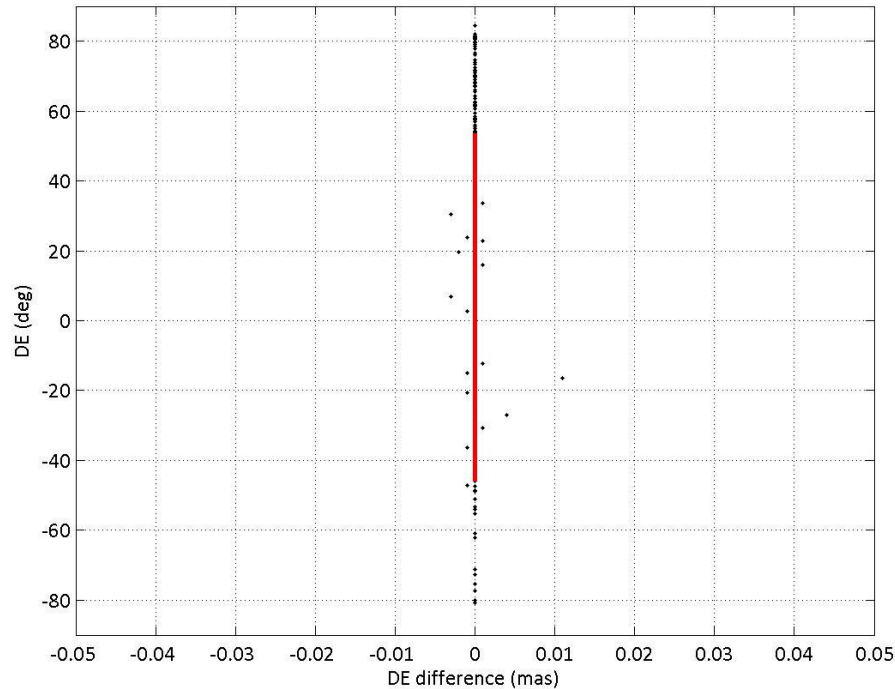
ITRF2000 vs. ITRF2008

- ITRF2000 (Altamimi et al., 2002):
136 VLBI stations, most of them mobiles with just a few occupations (here 46 in common)
 - Position 3-D wrms: 2 – 3 mm
 - Velocity 3-D wrms: 1 mm y^{-1}
 - Bad origin definition \rightarrow drift of origin in z-direction
- ITRF2008 (Böckmann et al., 2010; Altamimi et al., 2011):
113 VLBI stations, most of them mobiles with just a few occupations (here 46 in common)
 - Horizontal wrms: 1 mm, height wrms: 2 mm
 - Velocity 3-D wrms: 0.2 mm y^{-1}
 - No significant drift in z-direction

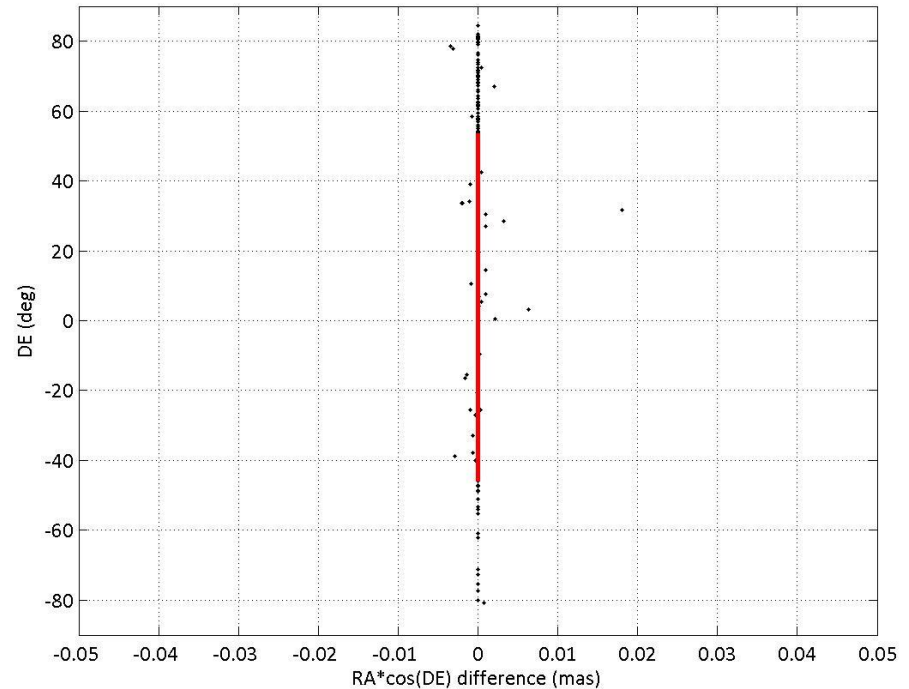
ITRF2000 vs. ITRF2008

- CRF: no effect,
max. DE-/RA-differences about $10 \mu\text{as}$ (below axes stability level of ICRF2), good de-correlation of sources and stations

ITRF2000 vs. ITRF2008



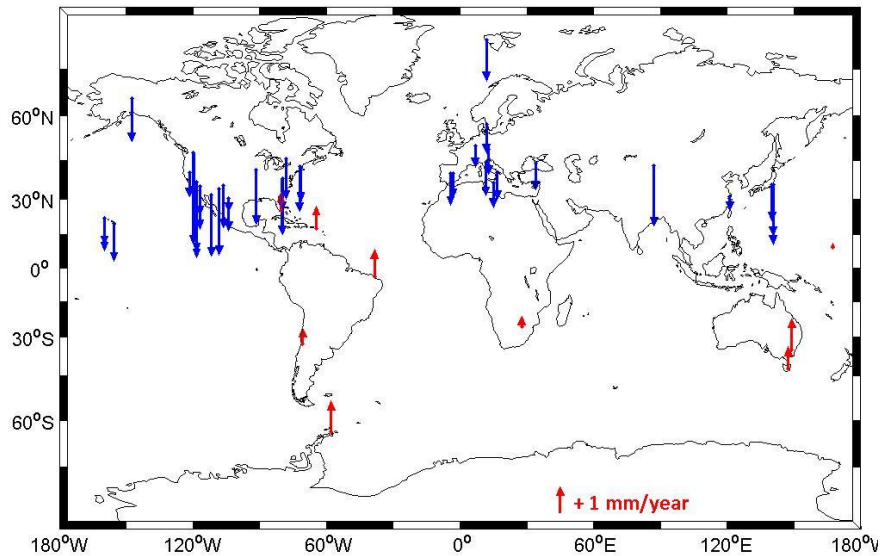
ITRF2000 vs. ITRF2008



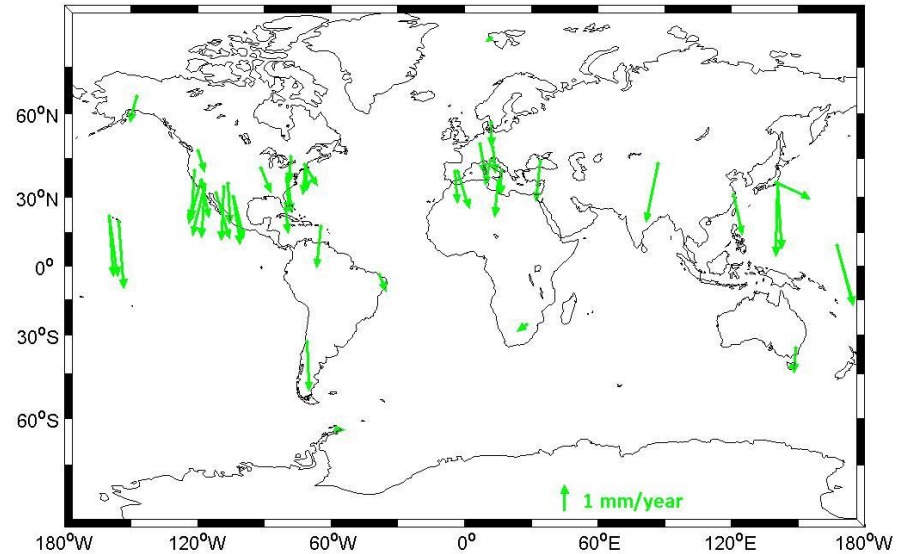
ITRF2000 vs. ITRF2008

- TRF: large effects, most significant are the velocity differences, max. velocity differences at 3 mm y^{-1} level, most significant in height and north component (origin drift in z-direction!)

ITRF2000 vs. ITRF2008: height velocity



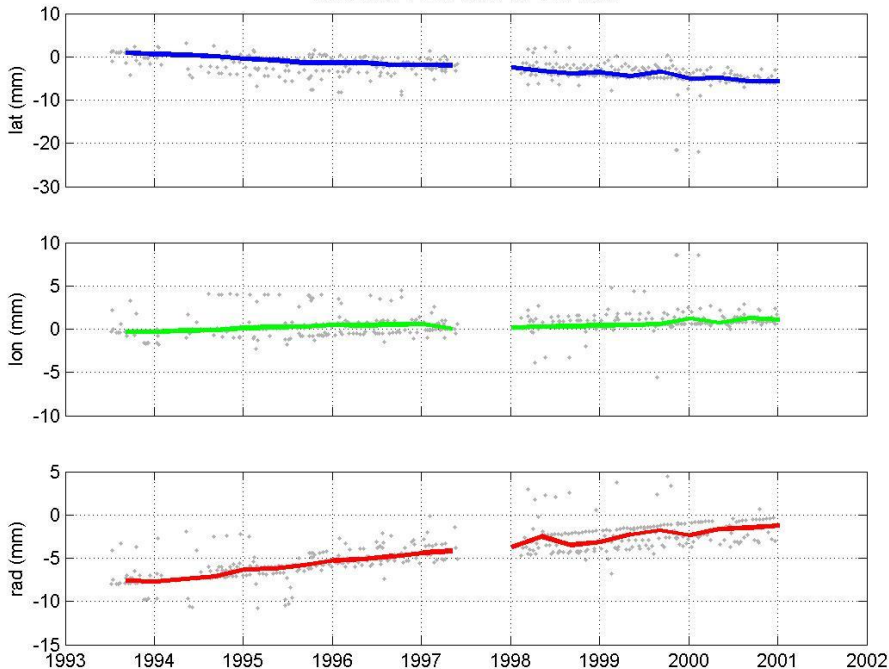
ITRF2000 vs. ITRF2008: horizontal velocity



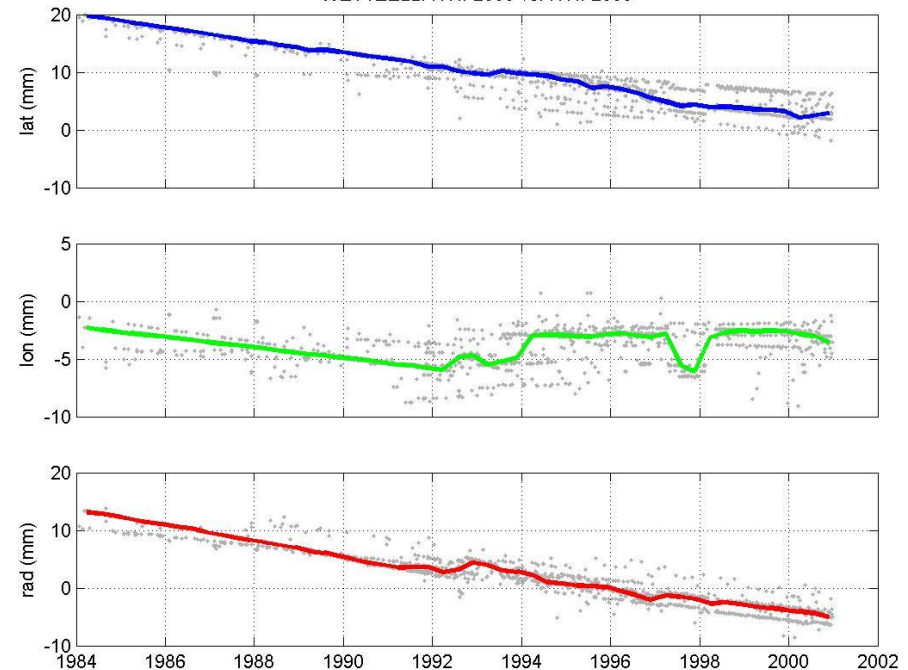
ITRF2000 vs. ITRF2008

- Station time series: large drift effects (also in East direction) → velocities of ITRF2000 are bad.
Some non-linear characteristics in station coordinates → various types of VLBI sessions have different potential to correctly adjust station coordinates

FORTLEZA: ITRF2000 vs. ITRF2008

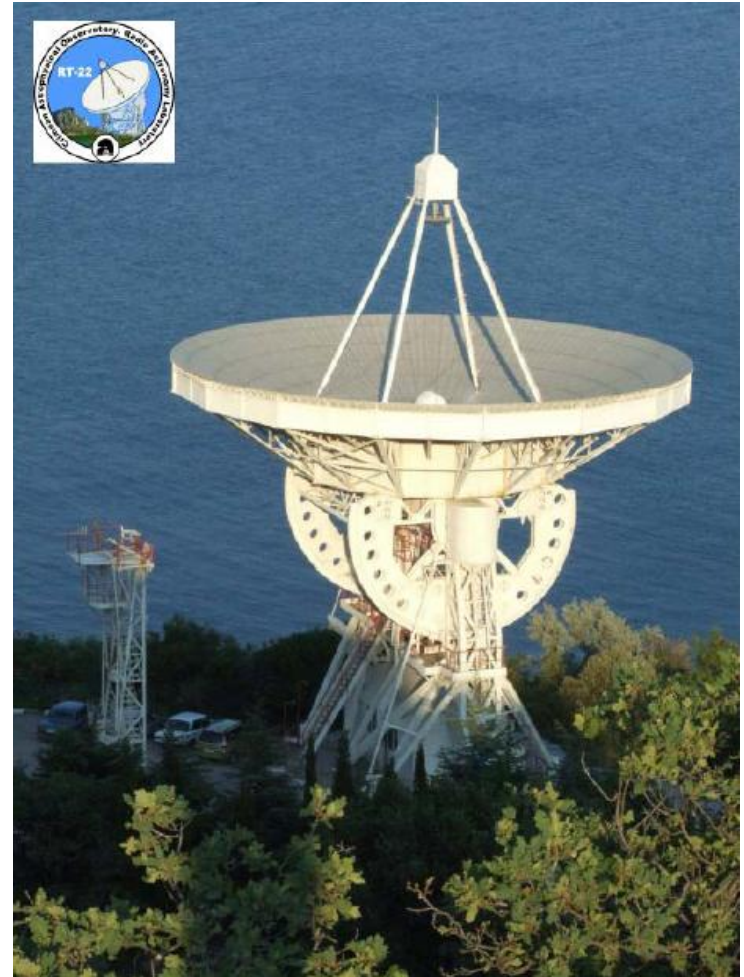


WETTZELL: ITRF2000 vs. ITRF2008



Ocean loading old vs. new

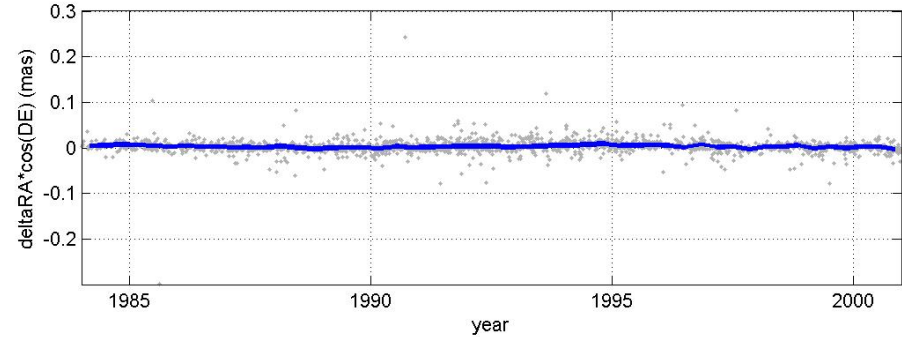
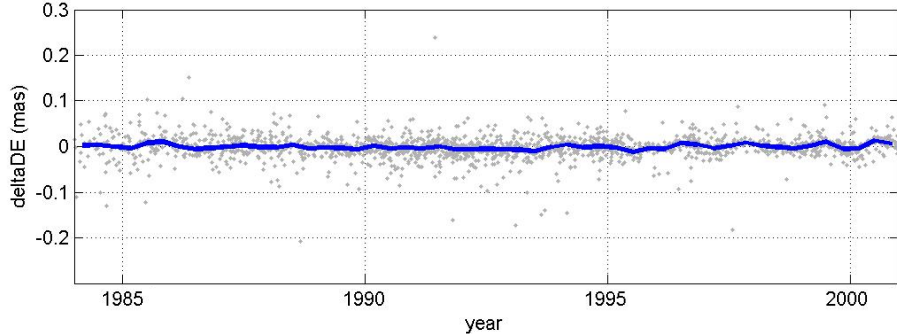
- Ocean loading deformation computed by Scherneck, based on the FES2004 (Letellier, 2004) ocean tide model
- Old: no convention (using the 9 main tides)
- New: using the 342 tidal constituents obtained by admittance theory (Agnew implementation)



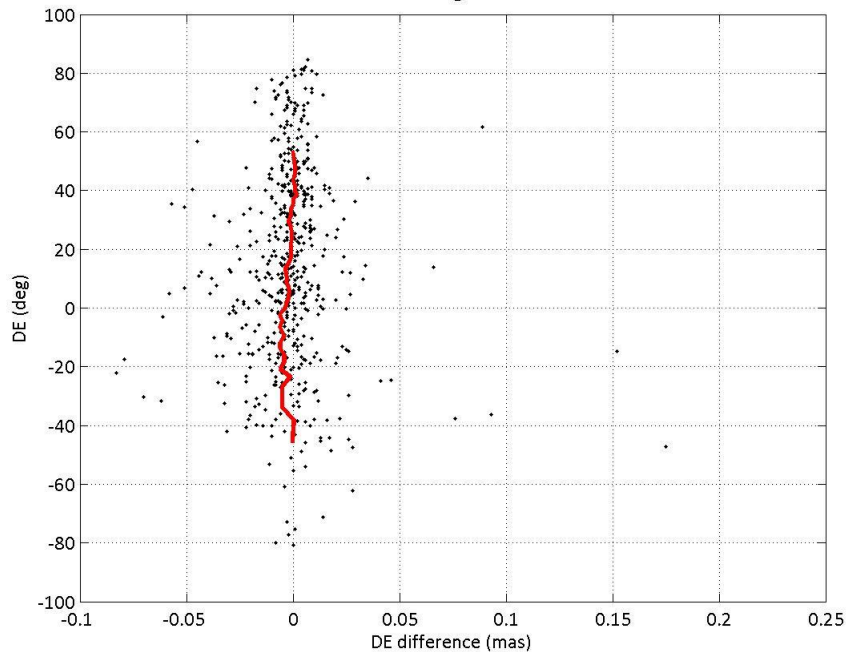
Ocean loading old vs. new

- CRF and radio source time series: noise around 40 μas level (mean positional error of ICRF2)

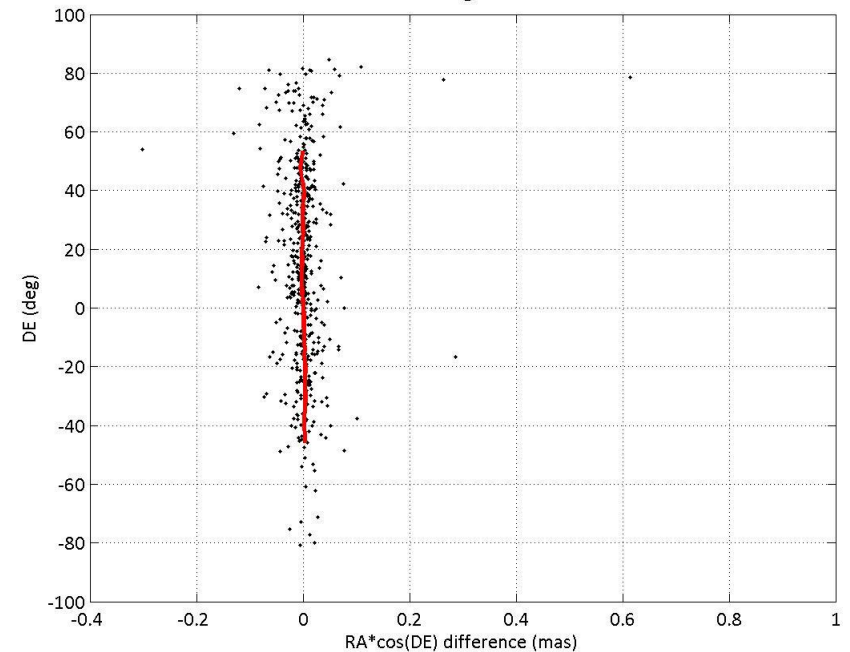
ocean loading new vs. old. 0851+202: 1709 sessions



ocean loading new vs. old



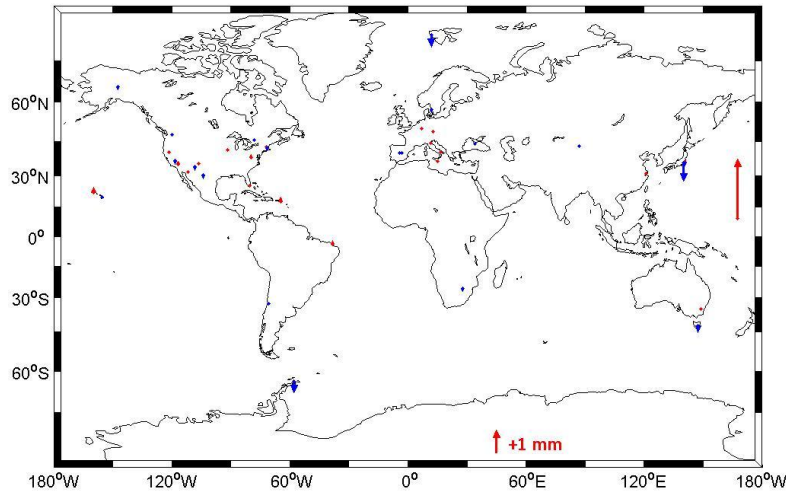
ocean loading new vs. old



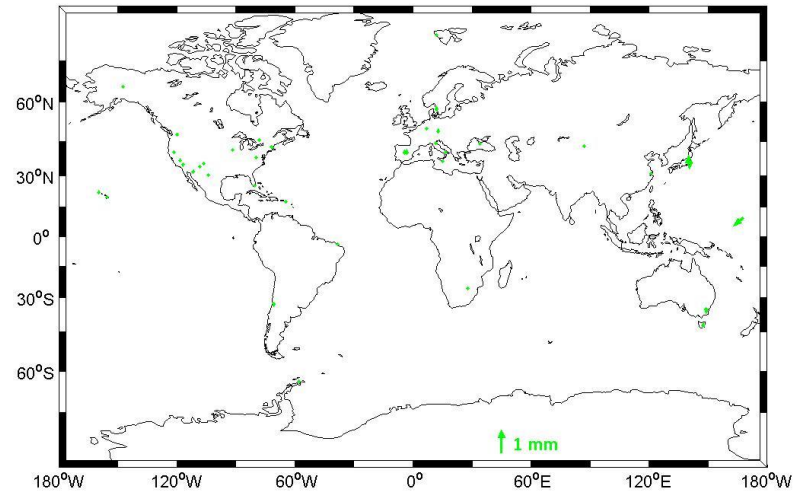
Ocean loading old vs. new

- TRF: No significant positional and velocity differences

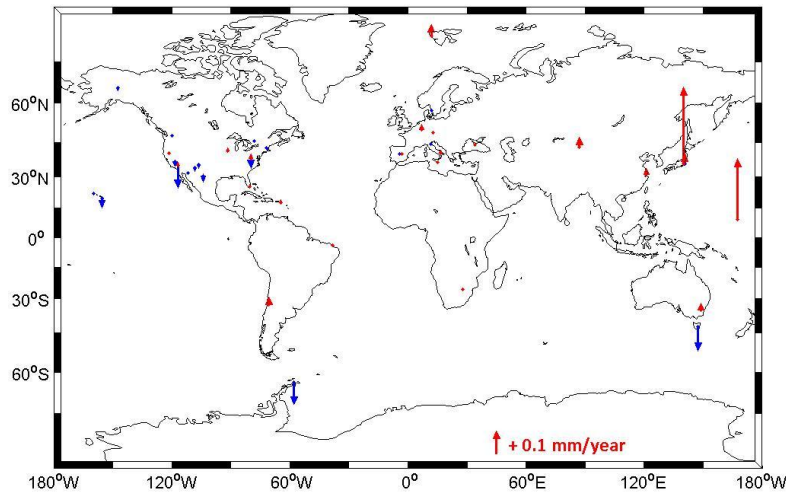
ocean loading new vs. old: height difference



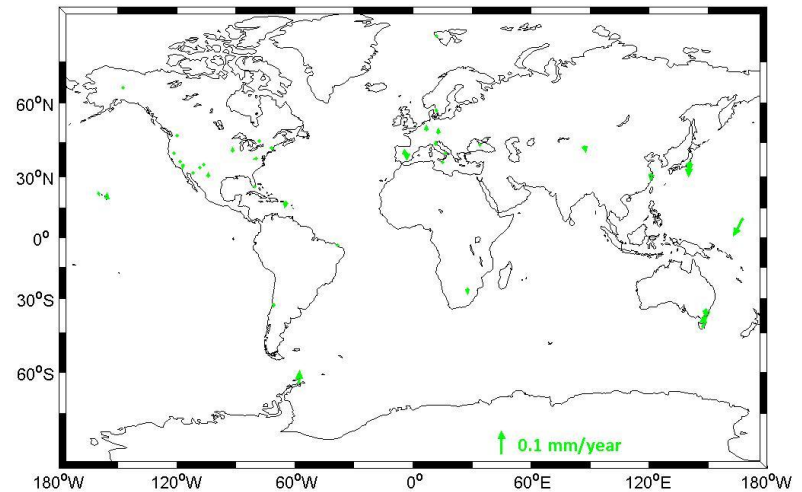
ocean loading new vs. old: horizontal difference



ocean loading new vs. old: height velocity



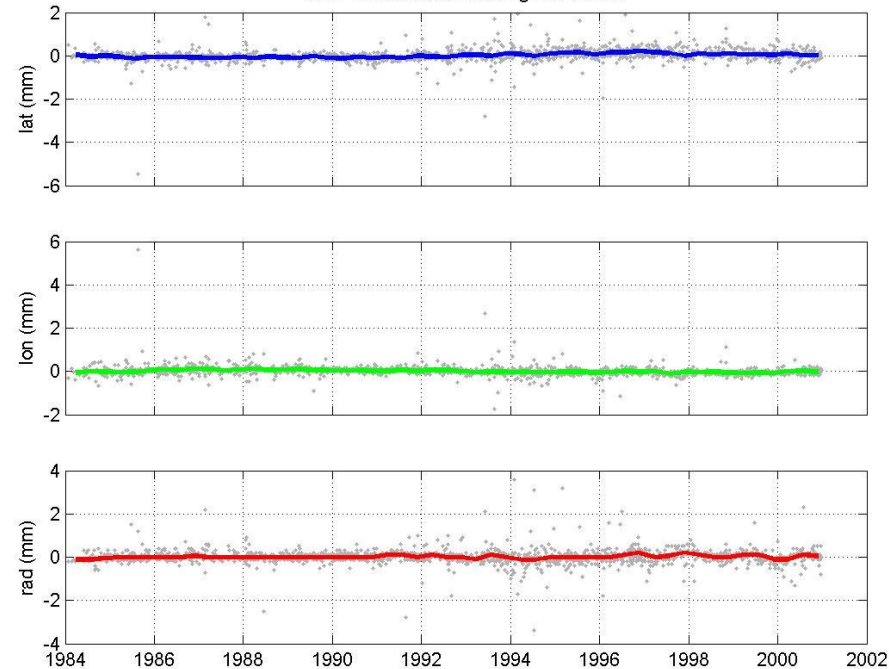
ocean loading new vs. old: horizontal velocity



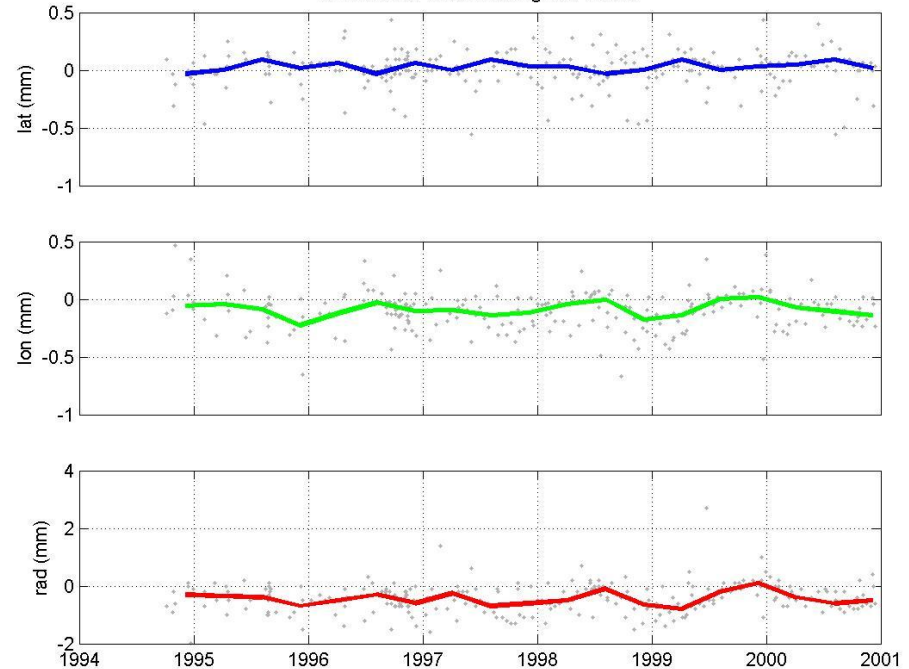
Ocean loading old vs. new

- Only station time series at higher latitudes and marine locations show small positional shift below 1 mm

WETTZELL: ocean loading new vs. old



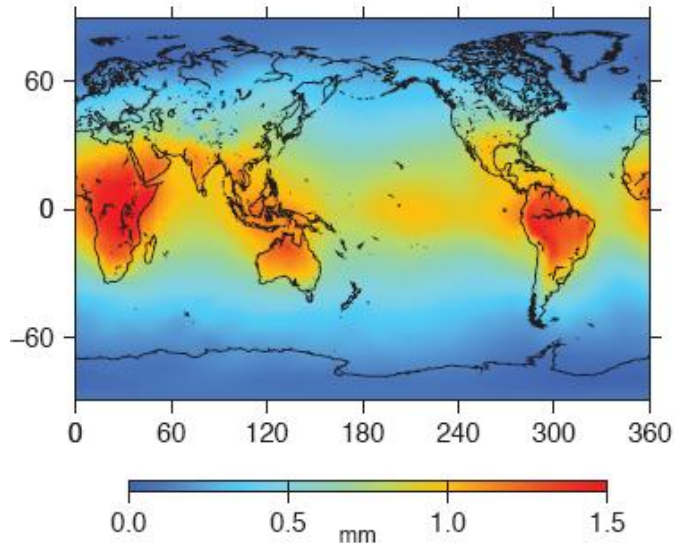
NYALES20: ocean loading new vs. old



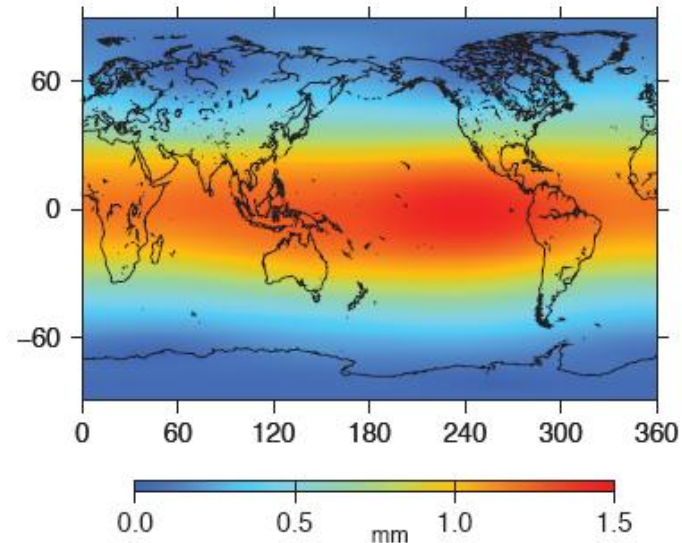
Atmosphere loading new vs. off

- Atmosphere loading deformation
- Old: no convention, Petrov & Boy (2004) – model was used for VLBI analysis depending on surface air pressure variations (NCEP)
- New: tidal (S1, S2) atmosphere loading, Ray & Ponte (2003) atmosphere tide model, implementation by van Dam

S1

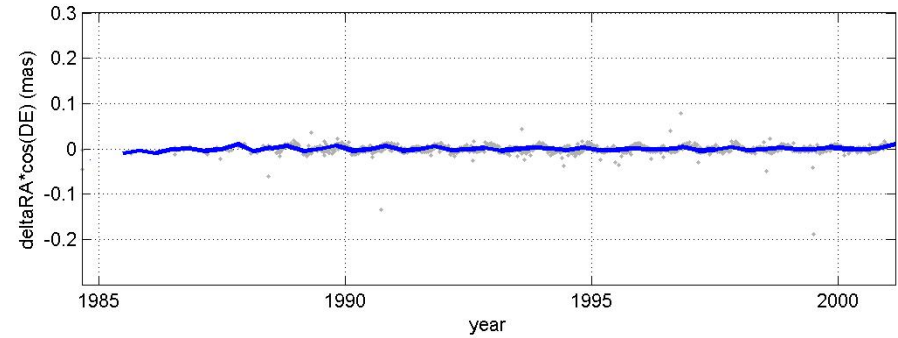
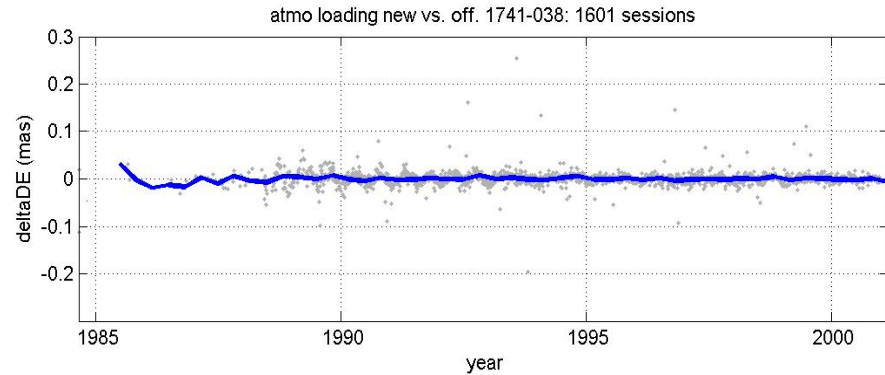


S2

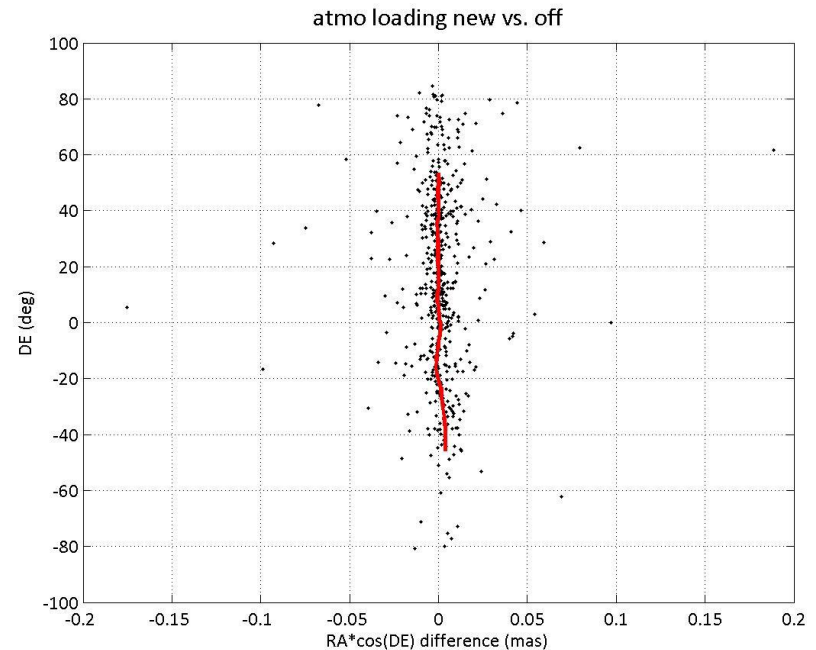
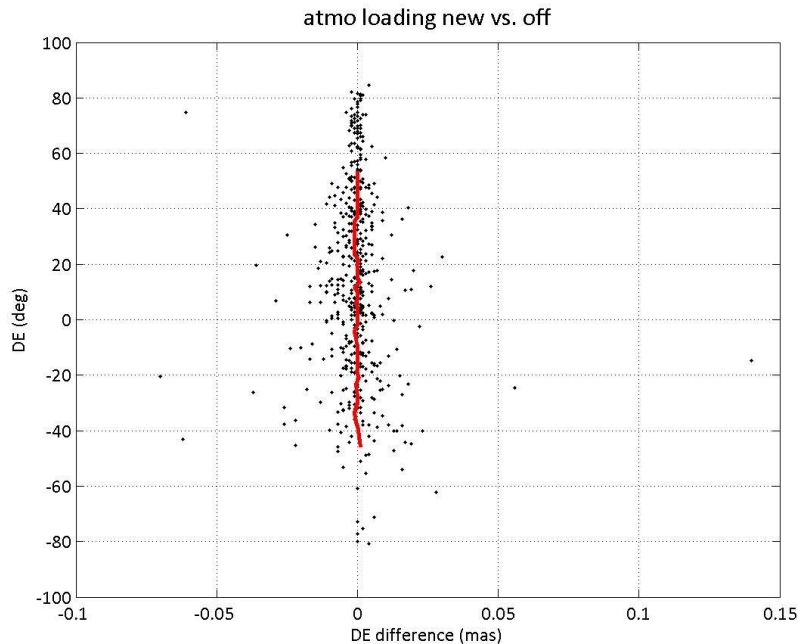


Atmosphere loading new vs. off

- Radio source time series: signals, max. 40 μas amplitude



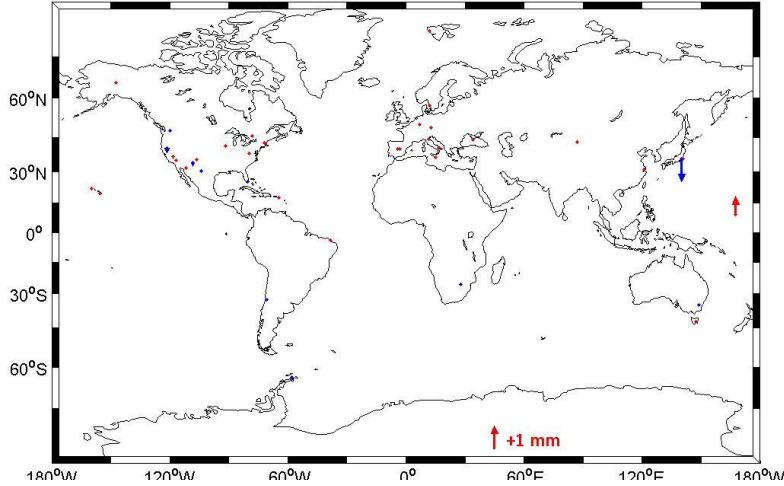
- CRF: no systematic effect, noise is about 20 μas



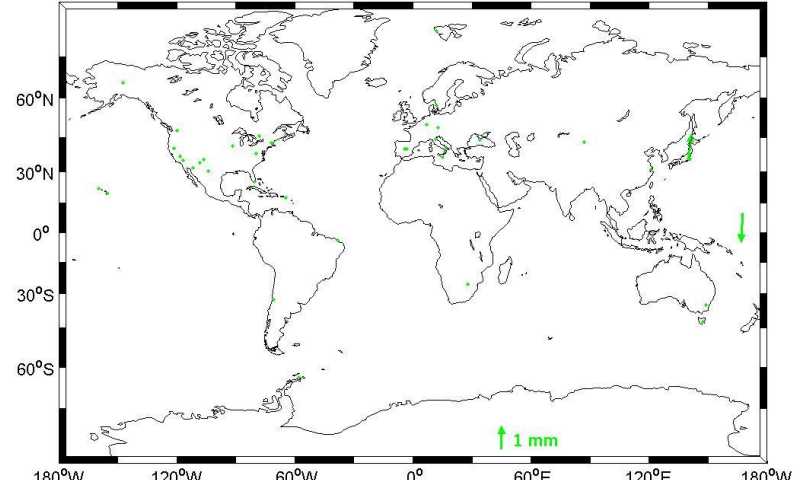
Atmosphere loading new vs. off

- TRF: no significant effect

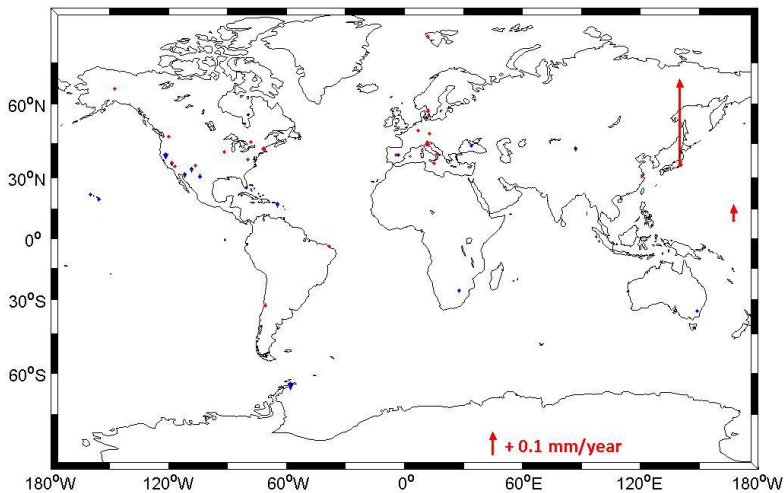
atmo loading new vs. off: height difference



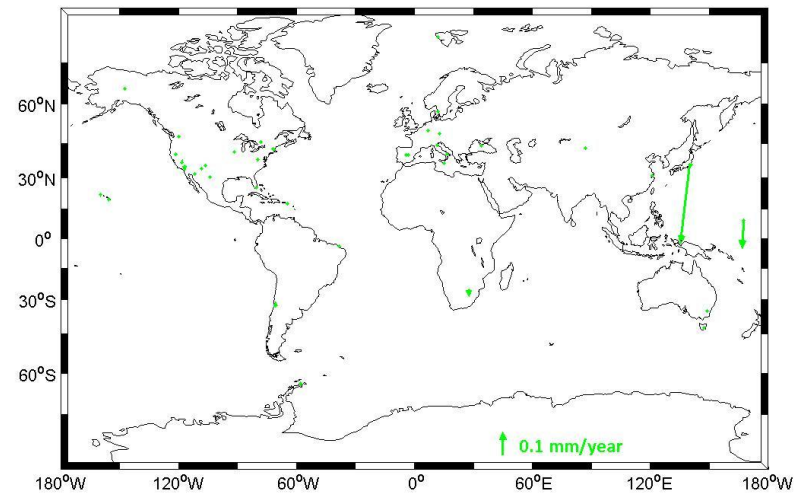
atmo loading new vs. off: horizontal difference



atmo loading new vs. off: height velocity

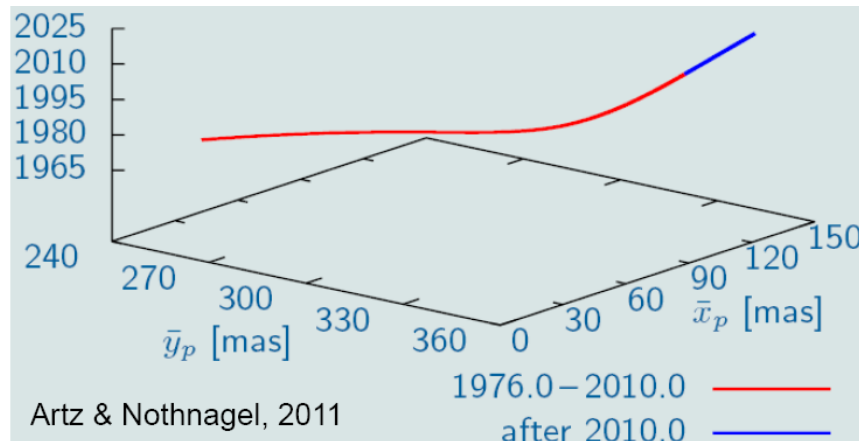
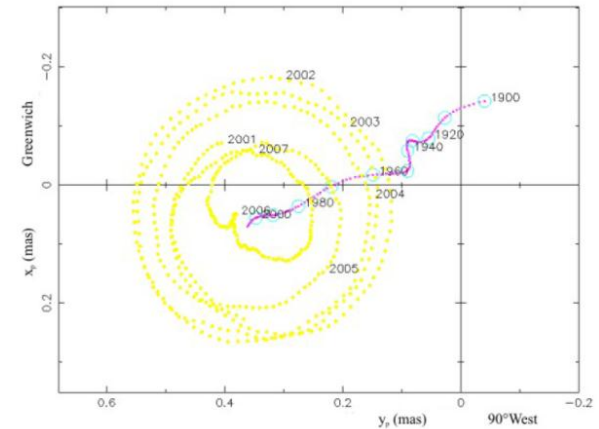


atmo loading new vs. off: horizontal velocity



Pole tide old vs. new

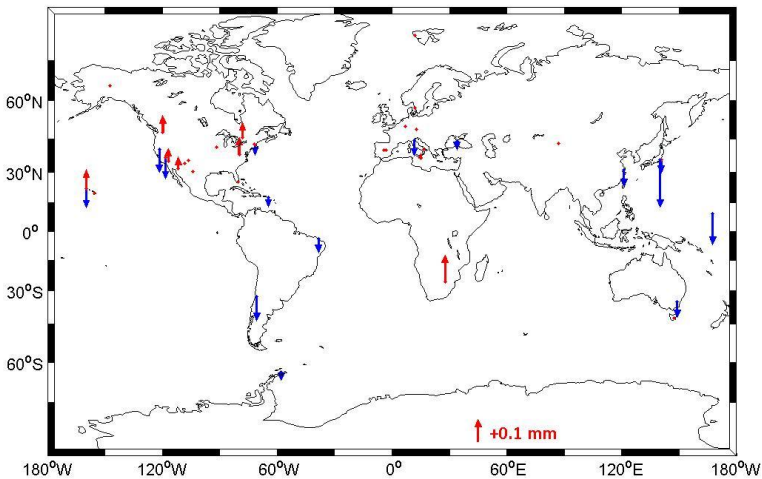
- Rotational deformation caused by mass variations of solid Earth due to the secular variation of polar motion described by a mean pole
- Old mean pole: linear model
- New mean pole: Piecewise cubic-linear model



Pole tide old vs. new

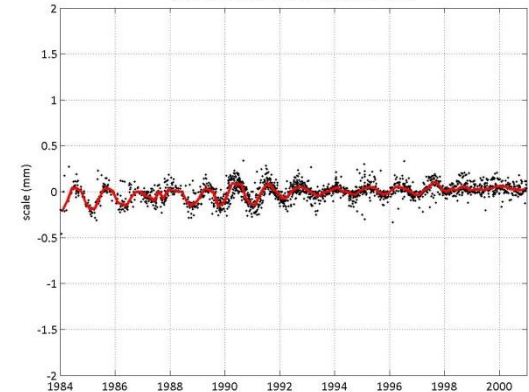
- CRF and radio source time series: no effect
- TRF: very small effects below the wrms of TRF, small signal in session-wise scale parameter (0.2 mm amplitude)

pole tide new vs. old: height difference

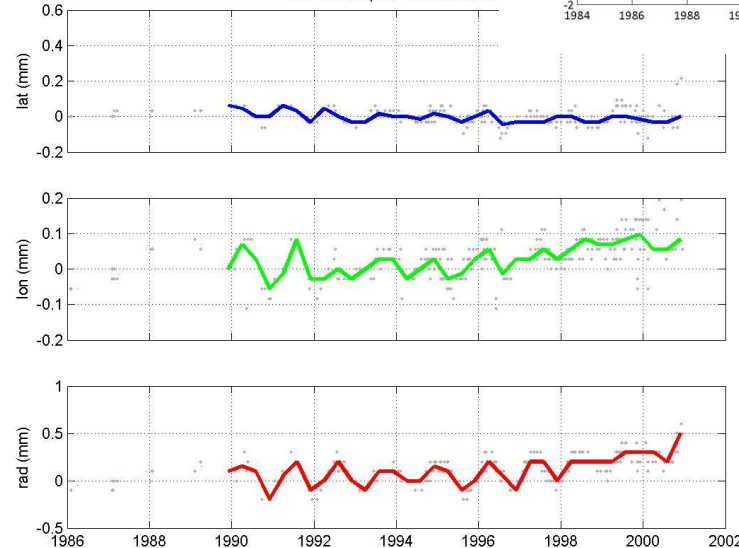


- Station time series: cubic effects, below 1 mm

pole tide new vs. old - network scale

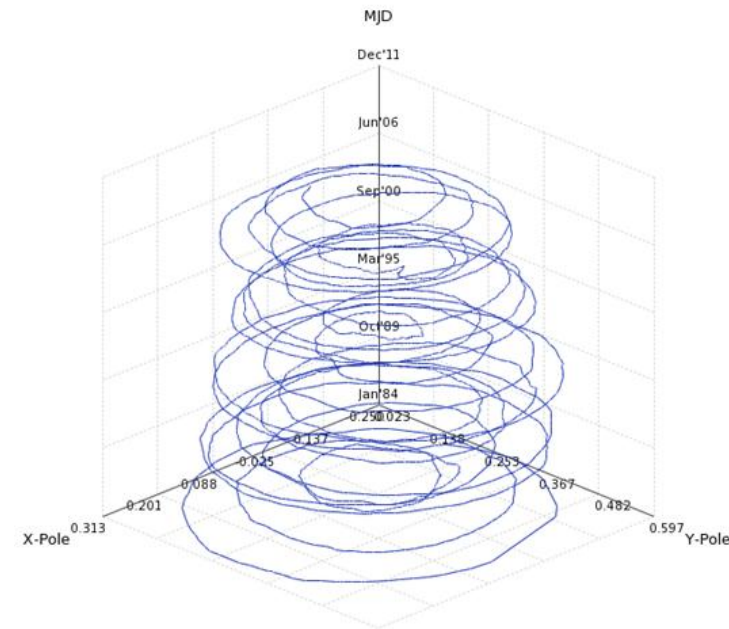


HARTRAO: pole tide new vs. ol



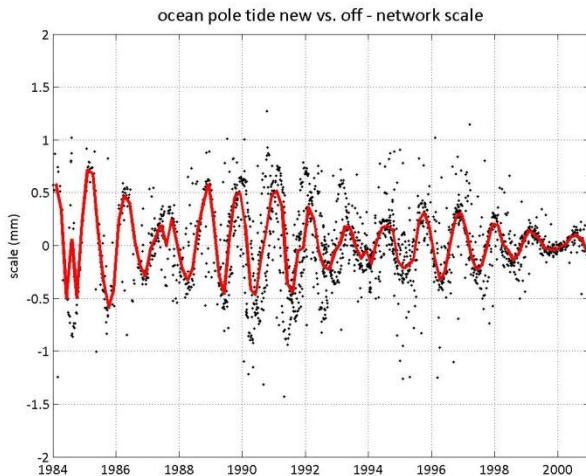
Ocean pole tide new vs. off

- Rotational deformation caused by ocean mass variations due to polar motion
 - Polar motion is dominated by the 14 month Chandler wobble and annual variations
 - Oceans are expected to respond in equilibrium at these long periods
-
- Old: no convention (no model)
 - New: Desai (2002) equilibrium model of the ocean pole tide

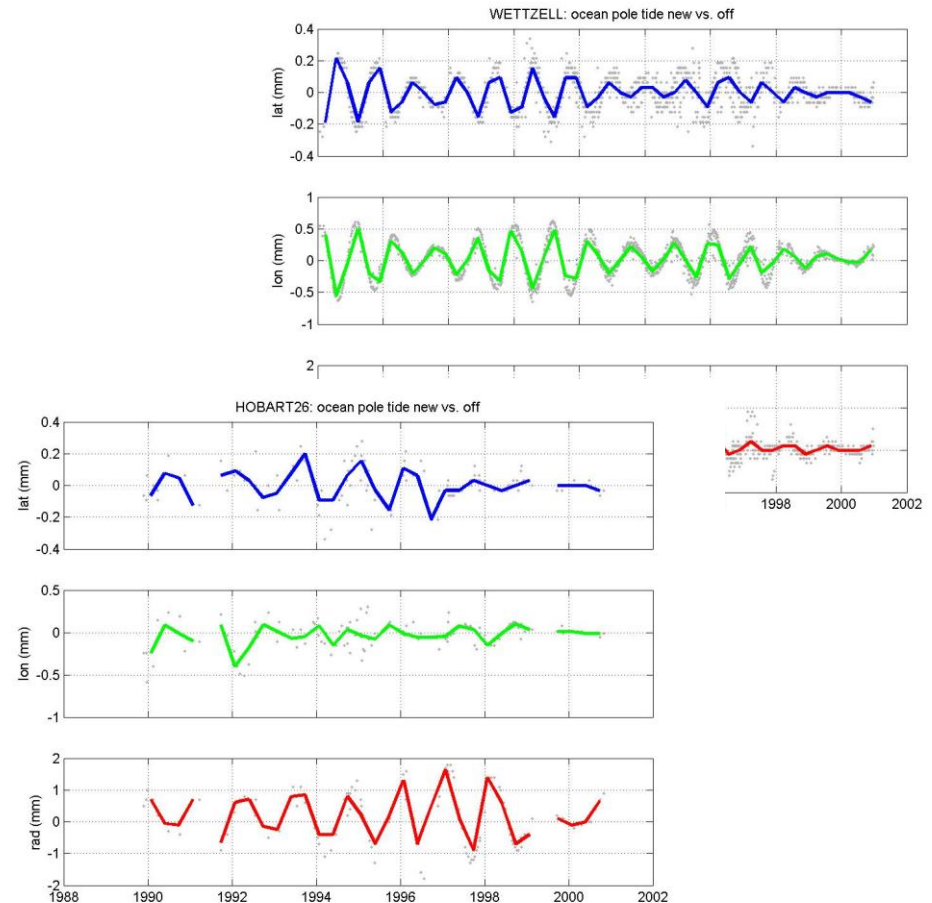


Ocean pole tide new vs. off

- CRF and radio source time series: no effect
- TRF: very small effects below the wrms of TRF, signal in session-wise scale parameter (0.5 mm amplitude)



- Station time series: polar motion signal with horiz. 0.5 mm, vert. 1.3 mm amplitudes



Ephemerides DE/LE 421 vs. 405

- Ephemerides effects on VLBI analysis are negligible
- Solid Earth tide modeling (Sun, Moon), difference between 421 (new) and 405 (old conventions) negligible
- VLBI delay model, gravitational delay (Sun, Jupiter, ...), difference negligible
- No effects on VLBI CRF/TRF

Summary

Reference Frames	TRF effects	CRF effects
ICRF-Ext.1 vs. ICRF2	-	noise 10 μas
ITRF2000 vs. ITRF2008	velocities 3 mm y^{-1}	-
DE/LE 405 vs. DE/LE 421	-	-
Displacements of reference points		
Ocean loading: 9 main tides vs. 342 constituent tides	higher latitudes and marine locations, positions < 1 mm	noise 50 μas
Atmosphere loading: new model Ray & Ponte (2003), van Dam	-	signals with 40 μas amplitudes
Pole tide: new mean pole	cubic effect < 0.5 mm	-
Ocean pole tide: new model Desai (2002)	polar motion signals max. 1.3 mm amplitude	-

Comments

- ITRF2008 and ICRF2 are clearly more accurate than their predecessors; ITRF2000 should not be used
- The new ocean pole tide model shows good and significant results
- This tidal atmosphere loading model affects radio sources not stations, the benefit from this model is questionable
- The Petrov & Boy (2004) atmosphere loading model was significantly better than the conventional one → why do we not apply it?
- The application of new IERS Conventions (2010) models gives not only improvements and many of the improvements are not significant (at the sub mm – level)
- We recommend to carefully test new models before they are specified as being the current conventional models

Thank you for your attention.

We acknowledge the
International VLBI Service for Geodesy and Astrometry – IVS
for providing data of excellent quality.

